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nonlinearities, hence it is essential that
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describing the circuit in Fig. Write the equations as a second-order differential equation in $y(t)$. Assuming a zero ...

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open-loop controller, control theory introduces feedback. A closed-loop controller uses feedback to control states or outputs of a dynamical system. Its name comes from the information path in the system: process inputs (e.g., voltage applied to an electric motor) have an effect on

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the process outputs (e.g., speed or torque of the motor), which is measured with ...

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